

# Cool Pi 4 Model B User Manual

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## Chapter 1 Getting to Know Cool Pi

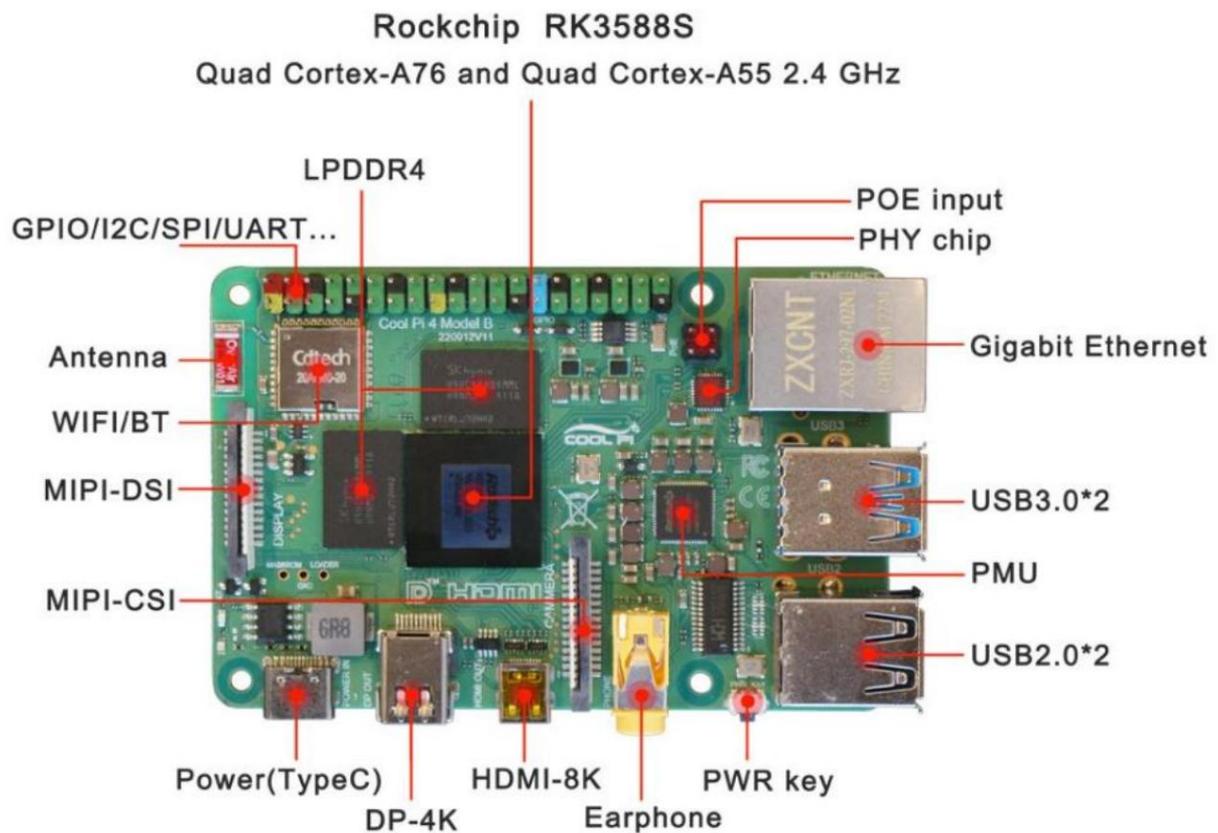
Embedded Linux development boards have been popular for many years, and choosing a suitable development board is particularly important for students and many embedded enthusiasts. A good discussion community and rich learning materials can lower the learning threshold, deepen interest in exploring new fields, and quickly get started with creative design.

Official technical forum: <https://www.cool-pi.com>

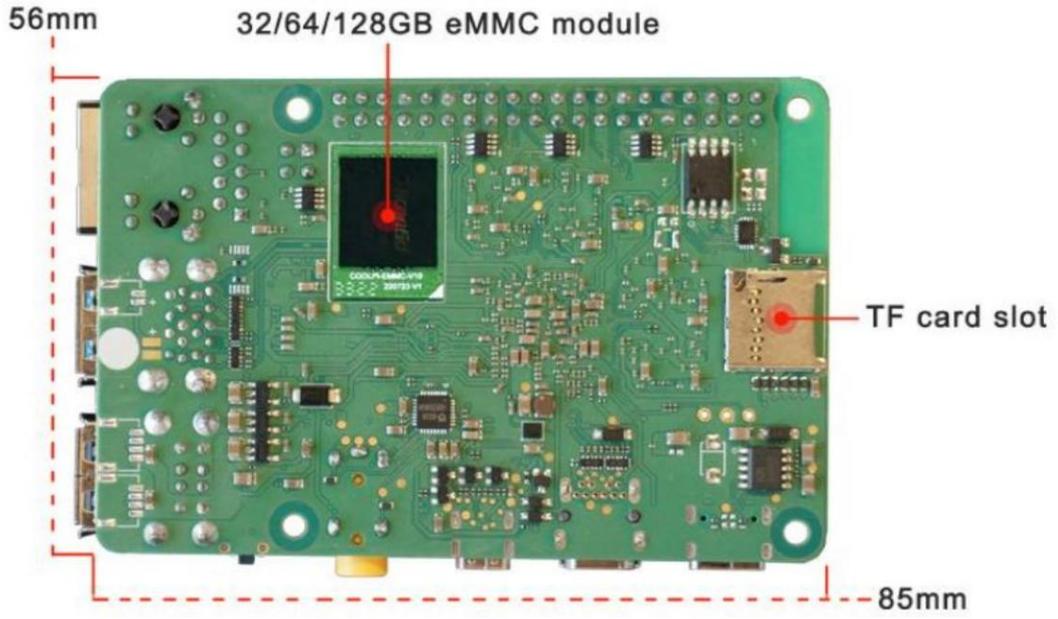
### 1.1 Hardware interface

CoolPi 4B has a wealth of hardware interfaces, covering common communication buses in the embedded industry, such as I2C, SPI, UART, CAN, etc. In terms of multimedia audio and video, micro HDMI supports up to 8K60 frame video output. The 8-core CPU up to 2.4Ghz can meet the daily multi-tasking requirements, such as server, gateway and other application scenarios. The built-in NPU has 6T computing power, which greatly enhances the realization of various model algorithms.

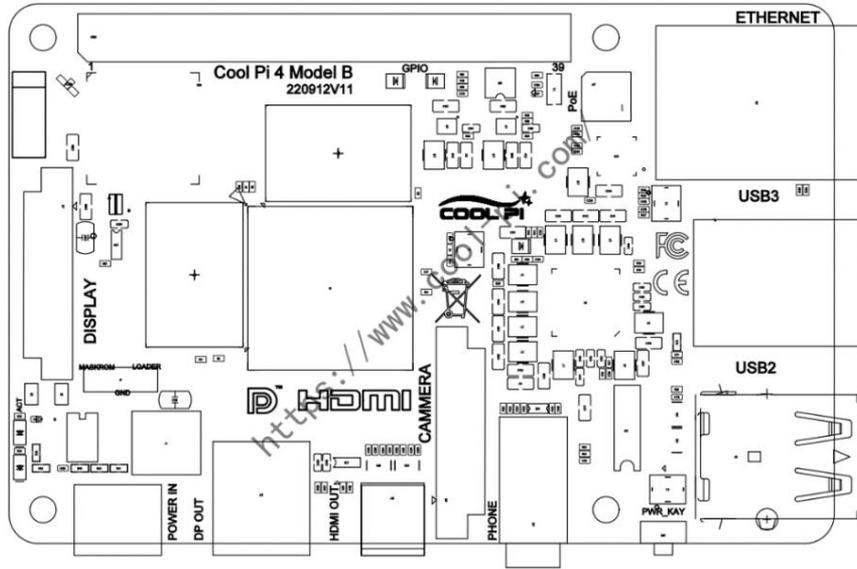
CoolPi 4B motherboard schematic diagram and related structural diagram files can be downloaded in the hardware area of the forum.



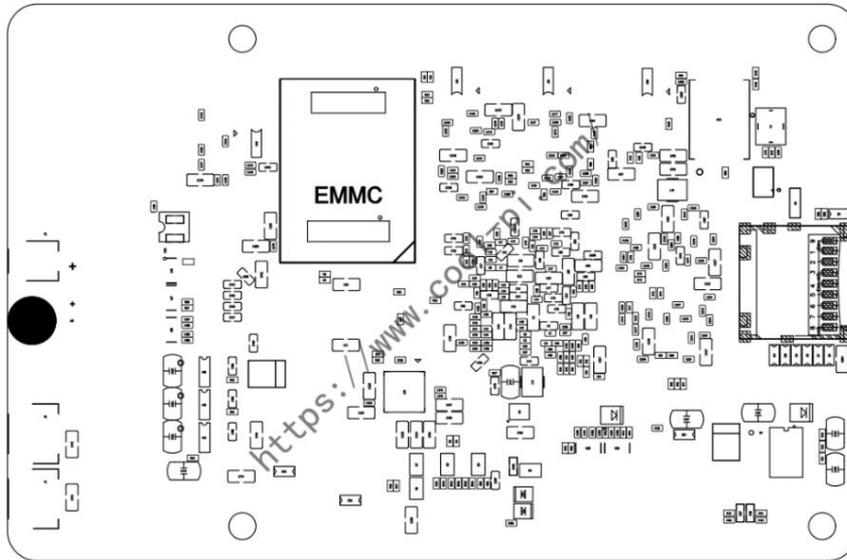
Motherboard reference picture front



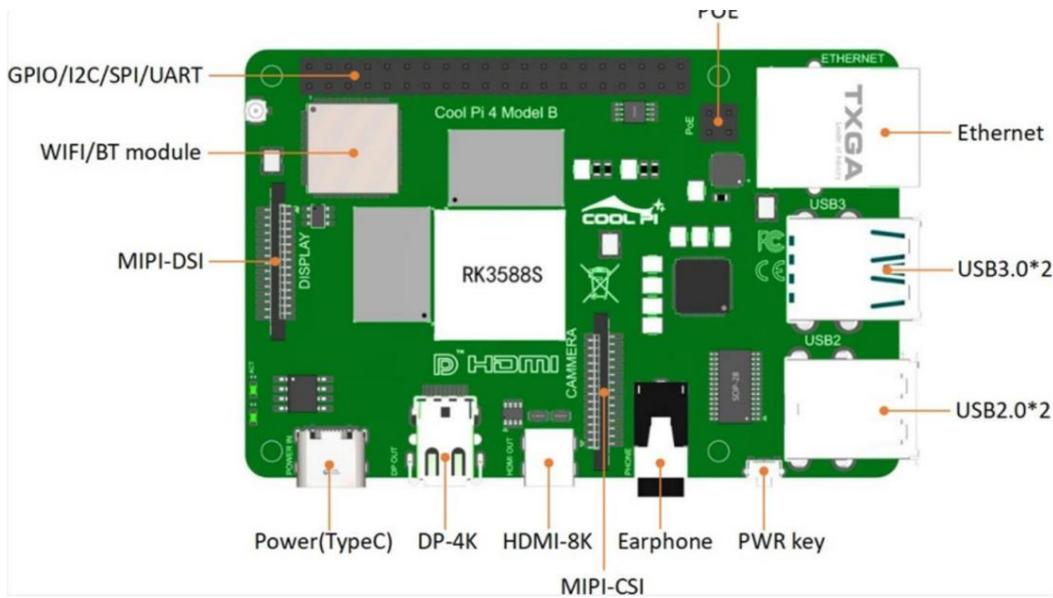
Motherboard Reference Picture Back



Motherboard bitmap front



Motherboard bitmap on the back



Reference diagram

(The lower left in the figure is No. 1, the upper left is No. 2, the lower right is No. 39, and the upper right is No. 40) The functions of the 40-pin female header in the above figure are defined in the following table:

Default Signal Function Pin	pin Number	pin number	Default signal function
3.3V	1	2	5V
/dev/i2c1 sda	3	4	5V
/dev/i2c1 scl	5	6	GND
gpio 47	7	8	/dev/ttyS0 uart txd 3.3V TTL

GND	9	10	/dev/ttyS0 uart rxd 3.3V TTL
gpio 128	11	12	gpio 39
gpio 129	13	14	GND
gpio 130	15	16	/dev/ttyS2 uart txd 3.3V TTL
3.3V	17	18	/dev/ttyS2 uart rxd 3.3V TTL
spi mosi	19	20	GND
spi eyes	21	22	gpio 40
spi clk	23	24	spi cs 0
GND	25	26	spi cs 1
/dev/i2c6 sda	27	28	/dev/i2c6 scl
gpio 131	29	30	GND
gpio 132	31	32	pwm2
gpio 133	33	34	GND
gpio 134	35	36	gpio 138
gpio 135	37	38	gpio 139
GND	39	40	gpio 115

## Remark:

a) An RTC clock chip is integrated in the board, which is connected under the i2c6

node; b) The above gpio is the default code configuration, and some gpio can reuse other functions by changing the configuration, such as can, uart,

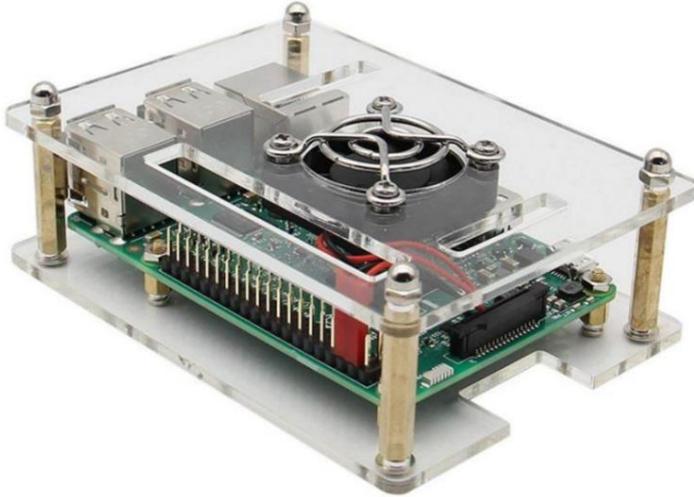
pwm, etc.; c) Power supply support Common TypeC interface adapter (DC5V~24V), please be careful if you use POE power supply  
Install POE expansion board to use (interface compatible with Raspberry Pi 4B).

## 1.2 Reference accessories

The appearance of

the DP display interface on the mainboard of the case radiator is higher than that of the Raspberry Pi 4B micro HDMI interface. Users need to pay attention when choosing a case. In addition, our motherboard has an independent power key to facilitate normal power on and off. Acrylic

shell <https://m.tb.cn/h.UOpDuvC?tk=mujsdT1adnn>



(It is recommended that the copper pillar choose a layer height of 30mm)

Share the 3D shell designed by the developer



(The forum has corresponding source files, thanks to the developers for sharing)

Display MIPI DSI

verification of a Weixue

5-inch screen <https://m.tb.cn/h.UIHlw8Y?tk=XGe2dgBBkk1>

微雪原装 5寸电容屏 DSI通信

5点触控, I2C触摸接口, 钢化玻璃面板



800×480 面板可选 低功耗

Both interfaces of

Micro HDMI

cable are available <https://m.tb.cn/h.UID0BqE?tk=5E8kdT1coli>



<https://item.m.jd.com/product/674875.html>

绿联



DP to HDMI cable

Mini DP interface can only support the standard DP protocol, the resolution can reach 4K P60, does not support INTEL DP++ protocol, so most of the ordinary Mini DP to HDMI cables on the market cannot be used. We verified two

cables for your reference [https://item.jd.com/](https://item.jd.com/100021518367.html)

[100021518367.html](https://item.jd.com/100021518367.html)



**十年 Mini DP转HDMI**

(Pay attention to choose active)

<https://item.jd.com/100018963014.html>



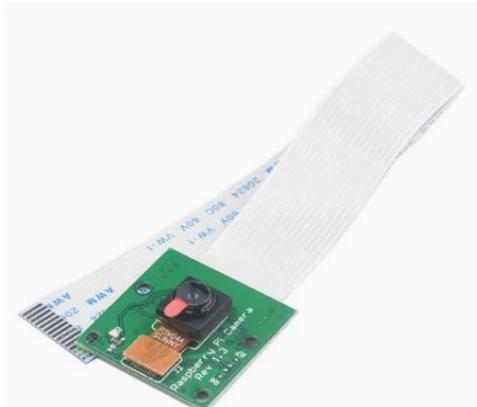
**1.8米**

**4K 60Hz**

**主动式Mini DP转HDMI**

Camera MIPI CSI verifies

an ov5647, accessories compatible with Raspberry Pi 4B



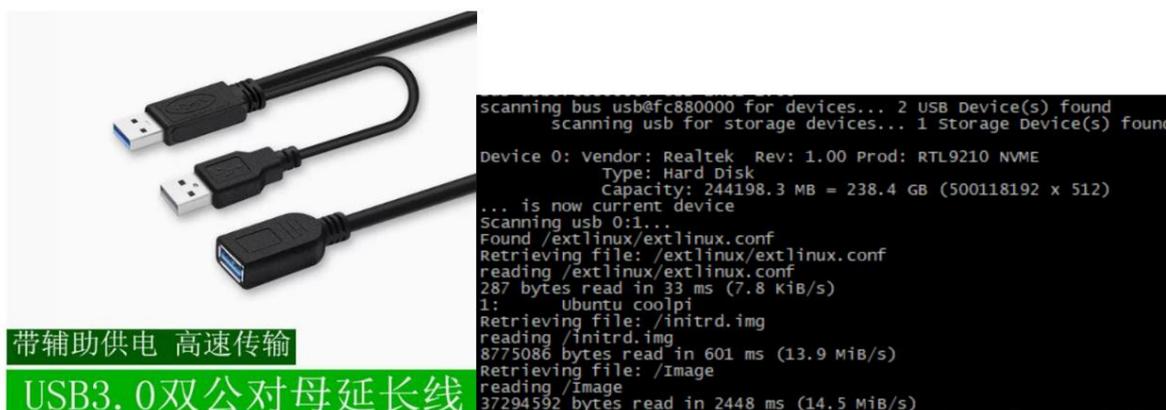


## Chapter 2 Getting Started with Cool Pi

CoolPi 4B supports a variety of disk boots, such as SATA, NVME hard disk (via USB cable),

U disk, TF card, eMMC, etc., can all be flashed offline. You can download the image file to any computer in advance, install the flash tool, and make a system disk. When you get the CoolPi 4B, plug in the boot disk and power it on to start it up, which is very convenient.

If you use USB3 to transfer the mobile hard disk, please pay attention to the hard disk power supply limit and increase the external power supply of the hard disk.

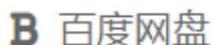


带辅助供电 高速传输

USB3.0双公对母延长线

### 2.1 Mirror address

CoolPi 4B provides reference images and related tools (via Baidu cloud download or Onedrive), and the open source code is hosted in the github repository. Developers are also welcome to share and exchange images.



<https://pan.baidu.com/s/1QV7RyMLqqK70ugYMxcXnbQ?pwd=qg2f>

OR

<https://coolpi>

[my.sharepoint.com/:f/g/personal/coolpi\\_coolpi\\_onmicrosoft\\_com/EuWQQ9Cxt0pKs2-](https://my.sharepoint.com/:f/g/personal/coolpi_coolpi_onmicrosoft_com/EuWQQ9Cxt0pKs2-)

[UxgJjFFABVwsC916i49ZcjPlxM9wq8w?e=DFiNvC](https://my.sharepoint.com/:f/g/personal/coolpi_coolpi_onmicrosoft_com/EuWQQ9Cxt0pKs2-UxgJjFFABVwsC916i49ZcjPlxM9wq8w?e=DFiNvC)

Most of the system login user name coolpi default password coolpi or 123

The system mirror is updated irregularly on the forum, please pay attention.

Now it supports various operating systems such as Armbian, Debian, Ubuntu, etc., and will continue to increase and expand support for other systems in the future.

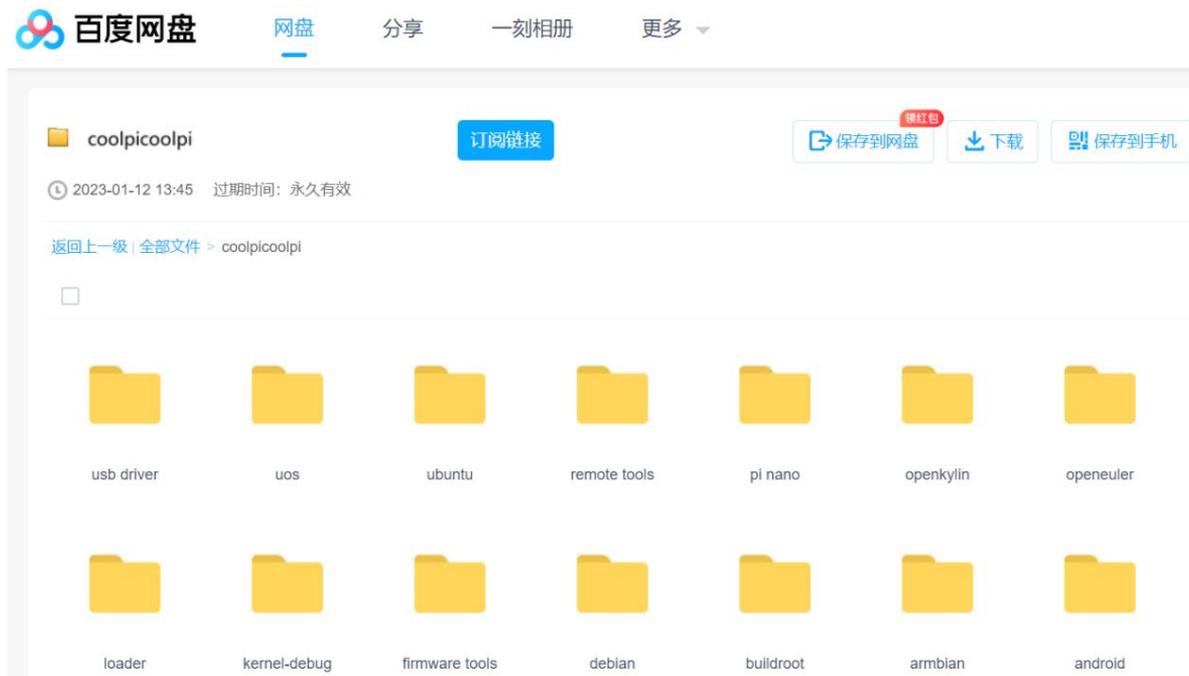
## 2.2 Mirror flash

CoolPi 4B supports multiple flashing tools, such as Win32DiskImager, balenaEtcher. The flash tool has no dependencies and can be operated on any computer. The following uses balenaEtcher as an example.

Download the flashing tool installation package from Baidu Netdisk



Optional System Firmware



We choose the Ubuntu20 image to introduce the operation process, download the image to the local and decompress it for backup.



Buying CoolPi 4B will give you a small adapter board, which is convenient for converting eMMC modules to TF cards. Buckle the eMMC module according to the triangle mark and connect it to the card reader

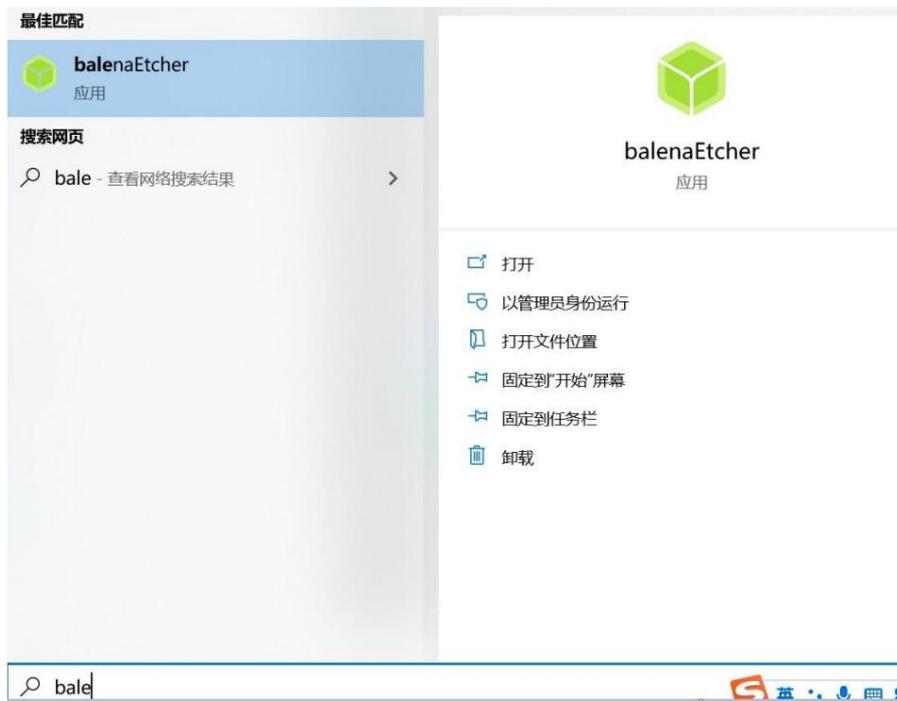


If it is not easy to insert into the card reader, grind the edge or cut it off with a knife and then insert it into the card reader

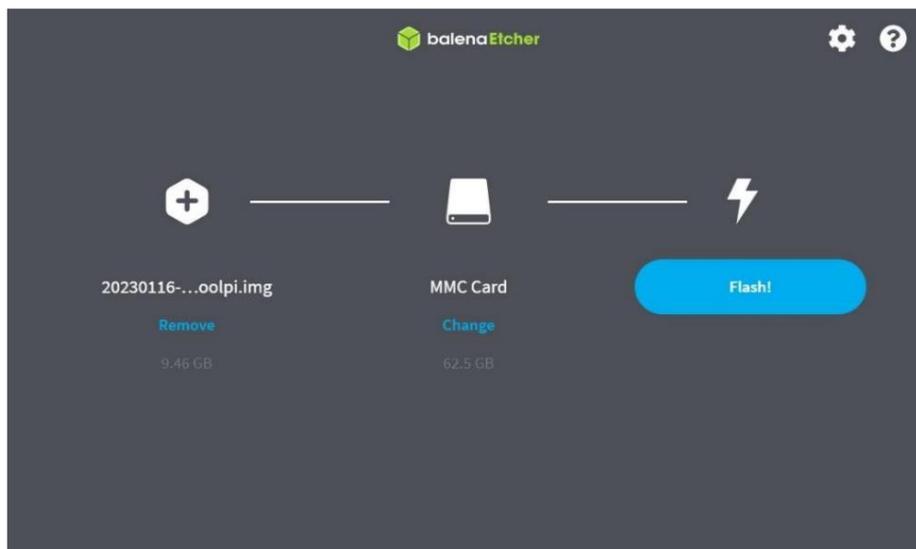




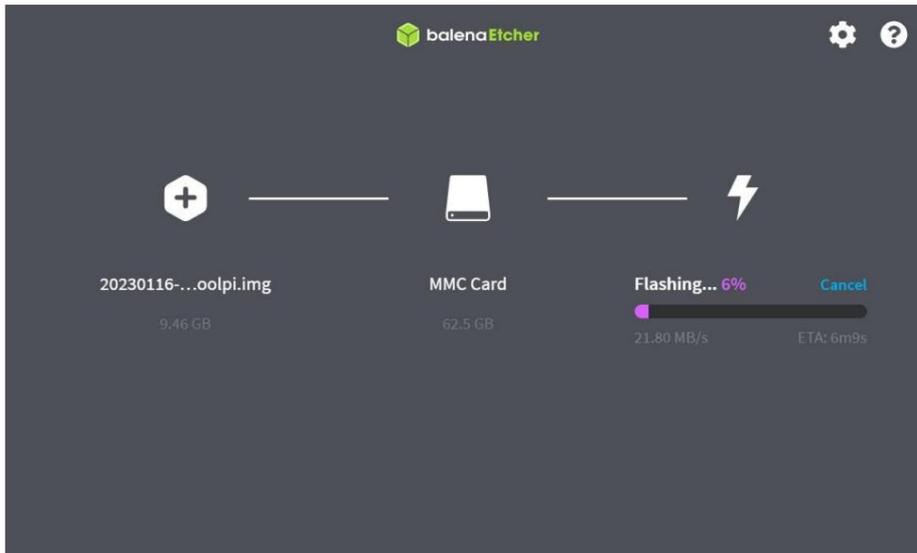
Open the burning software on Windows computer



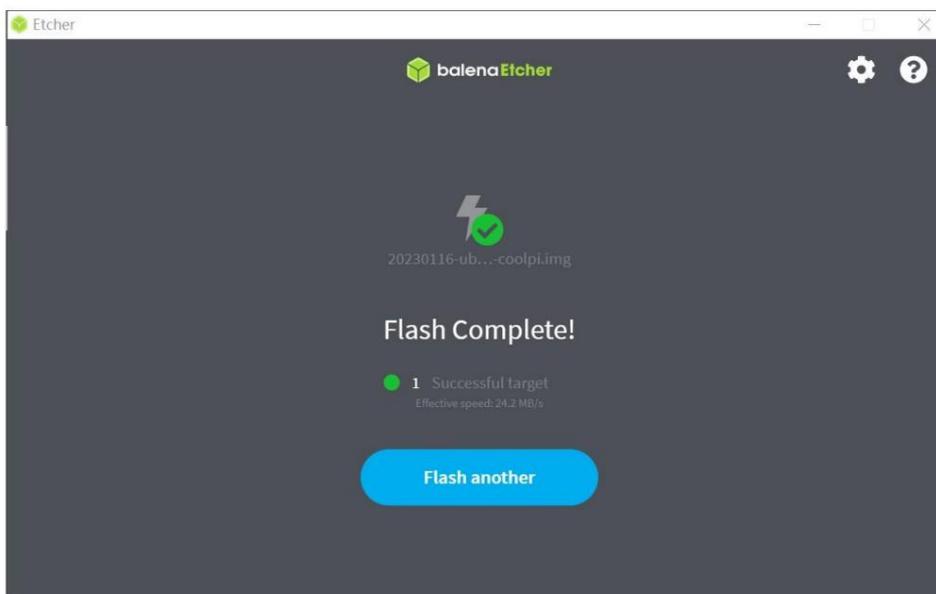
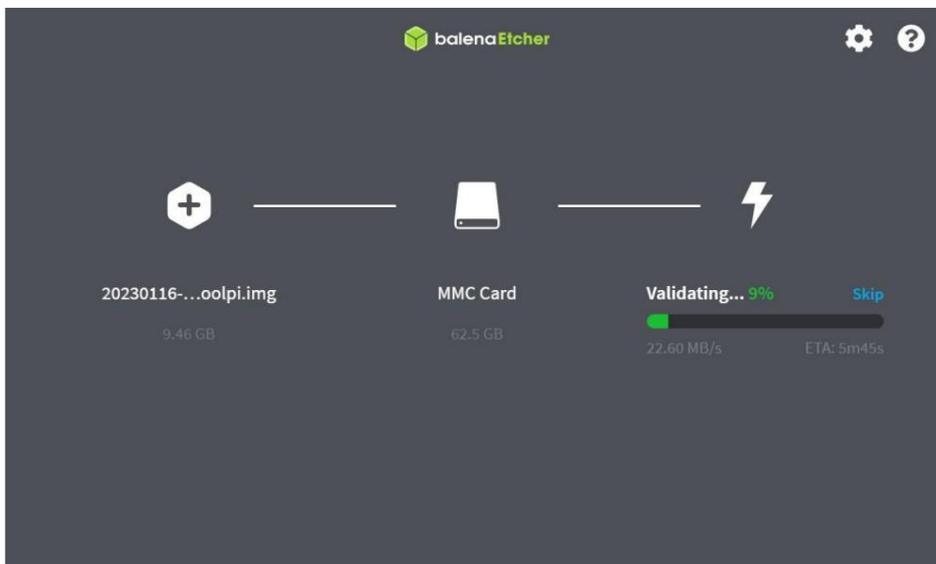
Select the image file, select the storage disk (be sure to choose carefully)



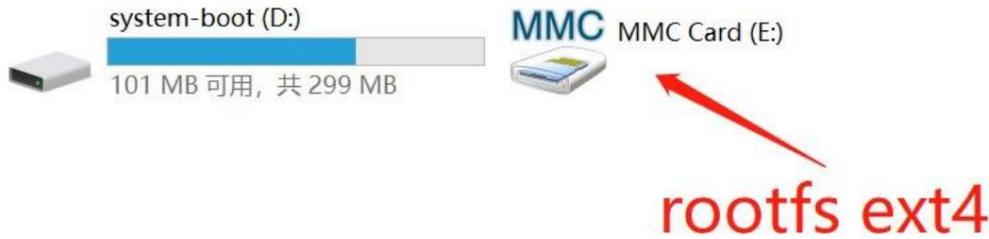
A pop-up window needs to obtain script batch processing permissions when starting, be sure to select Yes



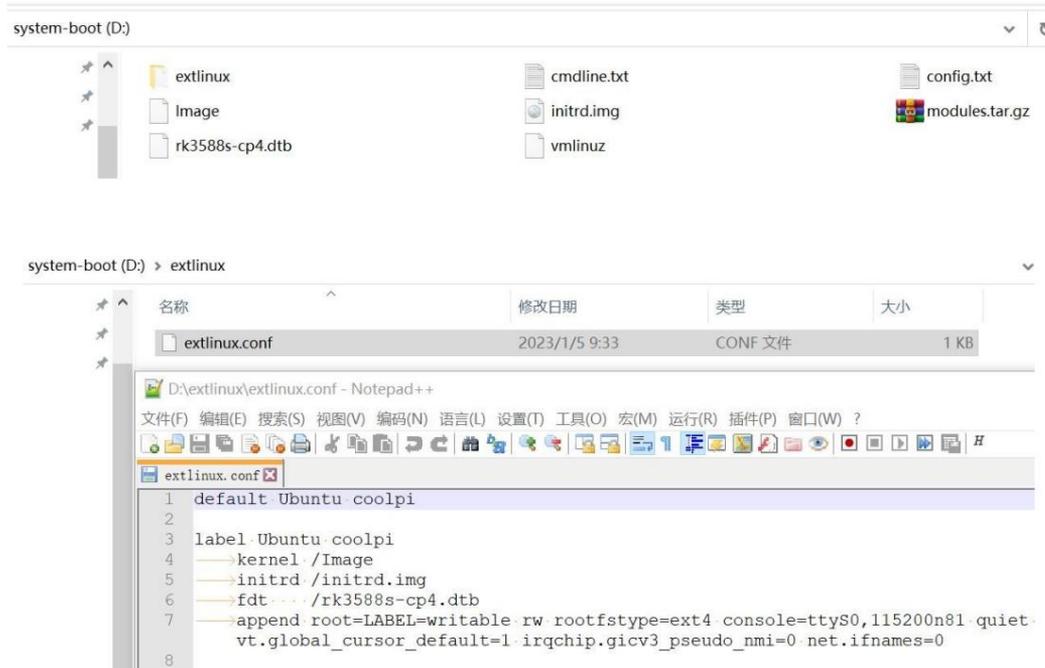
Waiting for burning verification



Re-plug the card reader, the computer automatically recognizes the eMMC partition, because Windows does not recognize the ext4 format partition, do not click to format the MMC partition here



The system-boot partition can edit and configure the linux kernel startup parameters according to the needs. Currently, extlinux.conf and cmdline.txt are supported, and extlinux.conf is read first.



Save and exit after editing. Safely remove storage devices



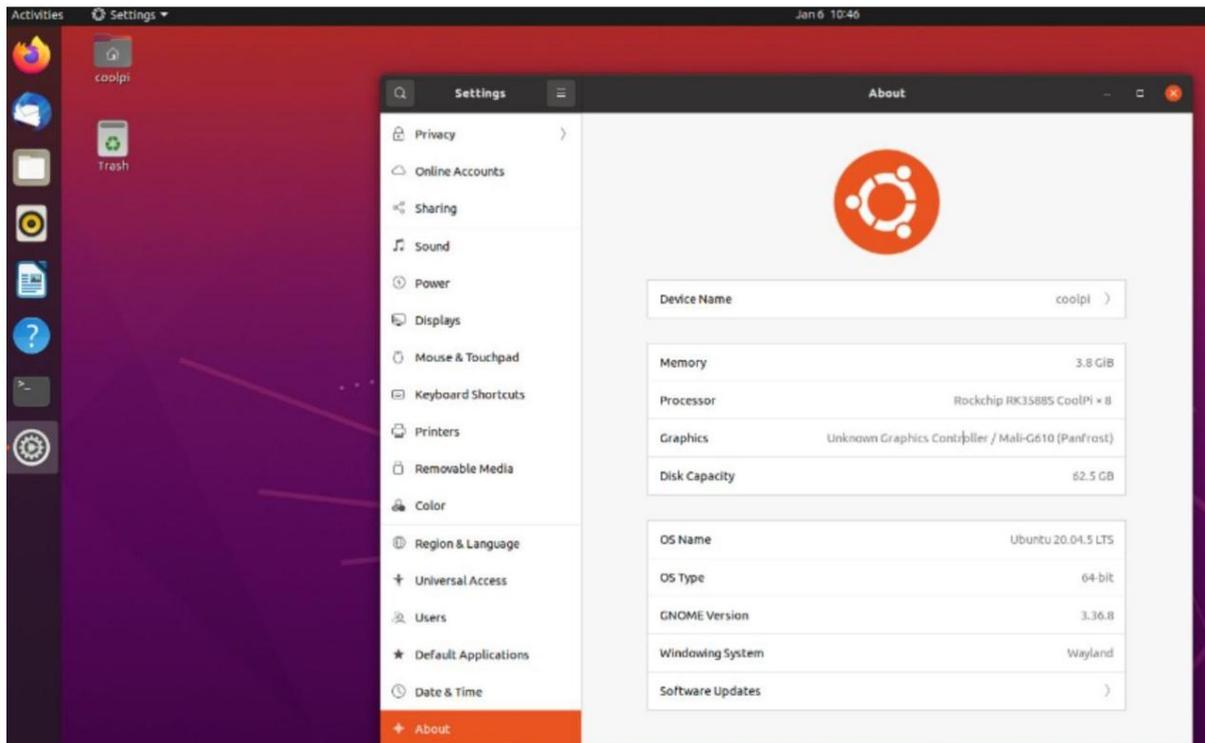
### Install eMMC on CoolPi 4B



Can also boot directly from USB port



Start the system to view eMMC capacity



Remark:

Please note that the device selects the disk to be flashed, and the data in the disk space will be cleared during the flashing process.

It is recommended to flash the machine in a linux system (Debian, Ubuntu, etc.) environment. Assuming that the disk node to be flashed is sdx, you can use the following command to complete it:

```
dd if=image.img of=/dev/sdx bs=1M status=progress;sync
```

### 2.3 Loader burning Cool Pi

4B open u-boot source code, the user can download the source file from the github warehouse, modify and compile according to the needs, and then download and update through the following operations.

Windows computer installation driver

[返回上一级](#) | [全部文件](#) > [coolpicoolpi](#) > usb driver

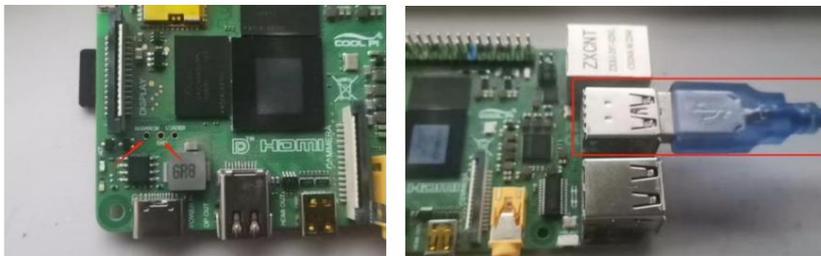
<input type="checkbox"/>	文件名	大小	修改日期
<input type="checkbox"/>	 DriverAssitant_v5.12.zip	9.4M	2023-01-12 14:52

Download the unzip flashing tool

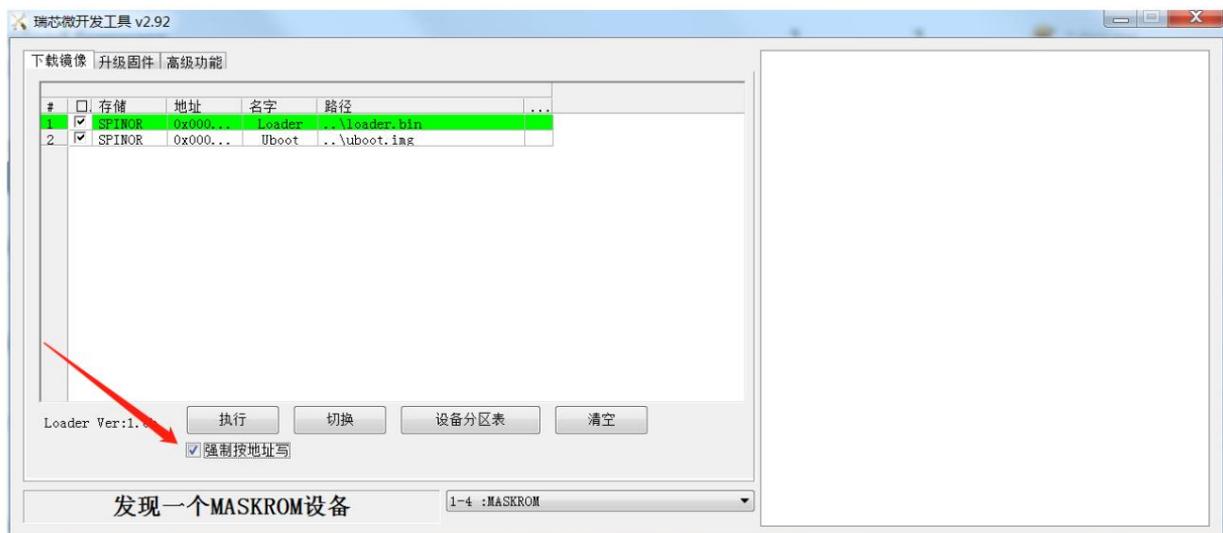
[返回上一级](#) | [全部文件](#) > [coolpicoolpi](#) > loader

<input type="checkbox"/>	文件名	大小	修改日期
<input type="checkbox"/>	 RKDevTool_Release_v2.92_loader0104.zip	4.3M	2023-01-12 13:45

Use tweezers to short-circuit the MASKROM and GND positions, and connect the double-ended TYPE A USB cable to the Windows computer



Keep the tweezers shorted, power on Cool Pi 4B, and perform programming



## Chapter 3 Develop Cool Pi

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CoolPi 4B opens the linux source code, which is convenient for developers to debug the kernel driver.

The corresponding image making method can be exchanged and discussed in the forum [www.cool-pi.com](http://www.cool-pi.com).

### 3.1 Kernel compilation

The linux kernel source code supports development and compilation in the X86-64 environment, and also supports direct development and compilation on the motherboard of this faction. The corresponding methods are the same, and the following uses the motherboard of this faction to run the Ubuntu system as an example:

download source code

```
ubuntu@coolpi:~$ mkdir test
ubuntu@coolpi:~$ cd test/
ubuntu@coolpi:~/test$ git clone git@github.com:yanyitech/coolpi-kernel.git
remote: Enumerating objects:
88605, done. remote: Counting objects: 100%
(88605/88605), done. remote: Compressing objects: 100%
(75148/75148), done.
```

Execute script compilation

```
ubuntu@coolpi:~/test$ ./build-kernel.sh
```

After the compilation is complete, the files generated in the source code out directory can be used to update the system or create a new image.

Execute the script to generate the coolpi-boot.img image file

```
ubuntu@coolpi:~/test$ ./build-fatboot.sh
```

3.2 Mirror image production

We provide armbian system production warehouse, please visit the official forum [www.cool-pi.com](http://www.cool-pi.com) for details

The CoolPi 4B system image file is divided into two partitions (actually more than one can be used, currently only two are used), the basic partition information is as follows:

Partition name label	Partition Format	Partition Size	Partition Content
system-boot the first partition,	FAT32	300MB	cmdline.txt config.txt initrd.img modules.tar.gz rk3588s-cp4.dtb vmlinuz Image extlinux/ extlinux.conf
writable	Second partition, ext4	According to the size of the system	rootfs system file + application + driver package

We create a 2GB image file as an example: a) Create img

and partition

```
~$ mkdir img_test` ~$ cd  
img_test/` ~/img_test$  
ls` ~/img_test$ dd if=  
dev/zero of=coolpi.img bs=1M count=2048`recorded 2048+0 read- in ` record 2048+0  
wrote ` 2147483648 bytes  
(2.1 GB, 2.0 GiB) copied,  
2.1999 s, 976 MB/s` ~/img_test$ fdisk coolpi.img
```

Welcome to fdisk (util-linux 2.31.1). Changes will stay  
in memory until you decide to write them to disk. Think twice  
before using write commands.

Command (type m for help): p

Disk coolpi.img: 2 GiB, 2147483648 bytes, 4194304 sector units: sector / 1 \*

512 = 512 bytes sector size (logical/

physical): 512 bytes / 512 bytes

I/O size (min/best): 512 bytes / 512 bytes Disk label type:

dos Disk identifier:

0xeeeeb672

Command (enter m for help): n

partition

type p primary partition (0 primary partition, 0 extended

partition, 4 free) e extended partition

(logical partition

container) selection (default

p): p partition number (1-4, Default 1): first sector

(2048-4194303, default 2048): last sector, +sectors or +size{K, M, G, T, P} (2048-4194303, default 4194303): +300M

Created a new partition 1 of type "Linux" with a size of 300 MiB.

Command (type m for help): t

Partition 1 selected

Hex code (enter L to list all codes): b

Changed the type of partition "Linux" to "W95 FAT32".

Command (enter m for help): n

partition

type p primary partition (1 primary partition, 0 extended  
partition, 3 free) e extended partition

(logical partition

container) selection (default

p): p partition number (2-4, Default 2): first sector

(616448-4194303, default 616448): last sector, +sectors or +size{K, M, G, T, P} (616448-4194303, default 4194303):

Created a new partition 2 of type "Linux" with a size of 1.7 GiB.

Command (type m for help): p

Disk coolpi.img: 2 GiB, 2147483648 bytes, 4194304 sector units: sector / 1 \*

512 = 512 bytes sector size (logical/

physical): 512 bytes / 512 bytes

I/O size (min/best): 512 bytes / 512 bytes Disk

label type: dos Disk

identifier: 0xeeeeeb672

	Start	Start	End	Sector	Size	Id	Type
device		2048	616447	614400	300M	b	W95 FAT32
coolpi.img1	coolpi.img2	616448	4194303	3577856	1.7G	83	Linux

Command (type m for help): w Partition

table adjusted.

Synchronizing disks.

~/img\_test\$

## b) Mount partition format write

~/img\_test\$ losetup -f /dev/loop18

~/img\_test\$

sudo losetup /dev/loop18 coolpi.img [sudo] xxx 's password: ~/

img\_test\$ ~/img\_test\$

sudo kpartx -av /

dev/loop18 add map loop18p1 (253:0): 0 614400 linear

7:18 2048 add map loop18p2 (253:1): 0 3577856 linear 7:18 616448 ~/

img\_test\$ ~/img\_test\$ sudo mkfs.vfat -F 32 /dev/mapper/loop18p1 mkfs.fat 4.1

(2017-01-24) ~/

img\_test\$ sudo fatlabel /dev/mapper/loop18p1 system-boot fatlabel: warning -

lowercase labels might not work

properly with DOS or Windows ~/img\_test\$ ~/img\_test\$ sudo mkfs .ext4 /dev/mapper/

loop18p2 mke2fs 1.44.1 (24-Mar-2018) Discarding device blocks: Finished creating filesystem with 447232 blocks (4k  
each ) and

112000 inodes Filesystem UUID: c4c8cda5-77ae-4872 The backup of

the -9f50-4d4c20cf048f superblock is

stored in the following

blocks:

32768, 98304, 163840, 229376, 294912

```
Allocating group table:
Done Writing to inode table:
Done creating log (8192 blocks)
Done writing superblock and file system account statistics: Done

~/img_test$ sudo e2label /dev/mapper/loop18p2 writable ~/img_test$ ~/
img_test$
sudo mount /dev/mapper/loop18p1 /mnt/ pre-prepare cmdline.txt
config.txt initrd.img modules.tar.gz rk3588s -cp4.dtb vmlinuz copy files to mount directory /mnt ~/img_test$
sudo umount /mnt/ ~/
img_test$ sudo mount /dev/mapper/
loop18p2 /mnt/ pre-prepare rootfs.tar.gz extract root file system
to Mount directory /mnt
Please pay attention to
decompress the driver package to /mnt/usr/
lib at the same time ~/img_test$ sudo
umount /mnt/ ~/
img_test$ sync ~/img_test$ sudo kpartx -dv /dev/
loop18 del devmap :
loop18p2 del devmap :
loop18p1 ~/img_test$ sudo losetup -d /dev/loop18
~/img_test$ losetup -f /dev/
loop18 ~/
img_test$
Congratulations on completing the image creation!
```

At this point, you can insert a USB flash drive or a mobile hard disk, and use the dd method to flash the new firmware.

### 3.3 Mirror backup

The CoolPi 4B system can perform backup extraction or recreate a new image at any time. The method is relatively simple, as described below.

- a) Insert the system disk into the linux system (Debian and Ubuntu are acceptable); b) Mount the two partitions of the system disk, which will be automatically mounted by the general system, please confirm the corresponding mounting directory; c) Open the terminal command line and copy the system -boot partition directory files are backed up to a local directory (such as /opt) ;
- d) Open the terminal command line, switch to the root authority, cd to the writable directory, and execute the compression command command `tar -czpvf /opt/rootfs.tar.gz *`
- e) Execute sync to refresh disk writing;

So far, the system image backup has been completed, and a new image can be created according to the instructions in Section 3.2.